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Dynamic Voltage Restores Using Renewable Energy

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Abstract: This work proposes a kind of voltage insertion into the grid through a dynamic voltage restorer (DVR) to compensate sagged and distorted voltage applied to sensitive load. The control to dynamically restore voltages applied to sensitive loads generates only voltage with the elemental frequency. The proposed method has the advantage of generates an easy waveform to compensate only the sag, this enables a extended battery lifetime of the DVR. As a consequence, restoration of the fundamental voltage, besides recomposing it to its nominal value, also attenuates the extent of THD within the load. Thus, this method also improves the facility quality of the system. A recursive least-squares is included to the system to estimate the harmonic components that compose the distorted voltage to be restored, instead of using filtering on the waveform.

In addition, the RLS doesn't contain delays, common to filters, which improves the performance of the system used. it's important to spotlight these harmonic components are not compensated by the restorer device. Their estimation has the function of reconstituting the distorted voltage digitally in the DSP. Simulation and experimental results are presented.

I. INTRODUCTION

Although the electrical power transmission and distribution systems have achieved a high level of reliability, electrical disturbances can't be entirely avoided. Some loadsmay not withstand disturbances in their voltage supply dueto economic or safety constraints, then the standard of suchelectrical power is of paramount importance.

In the scope of electricity quality, among the disturbances that affect the standard of electrical energy, those associated with short-term duration are the foremost frequent in energy systems. The impact of voltage disturbances in nationaleconomies, several surveyon costs that were administered by different entities during last years. Among all disturbances, voltage sags have the very best occurrence frequency [1].

Another important disturbance within the quality of electrical energy is that the incidence of harmonics on power grid components and loads. Harmonics are produced by nonlinear equipment, like discharge furnaces, variable speed drives and loads which use power electronics. Harmonics can cause defects in computer-controlled loads, transformer overheating and failed capacitor among other problems [2]. the assembly of pulsating torques and overheating in rotating machinery cans also are attributed to harmonics [3].

Among some alternatives made to make sure the standard of power supply for the load, the DVR has proven efficient and profitable [4], [5]. This equipment protects critical loads against mains voltage disturbances by imposing, through transformers serial with the load, compensation voltage levels such the load is protected and maintains sinusoidal voltages with constant frequency.

The primary function of a dynamic transformer is to protect critical loads from voltage sags and swells [6], [7]. However, these systems have their performance compromised in the presence of voltages with harmonic distortions [8], [9]. Then, DVR applications were developed to mitigate the consequences of harmonic distortions and voltage sags [10]–[12]. However, harmonic distortions are a permanent regime problem. In this way, the DVR shouldn't correct them as this is able to even be acting permanently, reducing the battery life.

This paper discusses the utilization of the harmonic estimation technique to estimate the elemental and harmonics in systems with voltage sags and harmonic distortions and perform only the restoration on the elemental component of the distorted voltage. For this, it's necessary to continuously monitor the signals of the



facility system and ensure fast and accurate responses to signal amplitude and phase. From this online estimate, the control will act to correct only the voltage sag and, thus, ensure an extended battery life for the DVR.

II. ESTIMATION OF THE GRID VOLTAGE WITH HARMONIC DISTORTION

In this section, an algorithm to calculate amplitude and phase of distorted AC voltage is described. the elemental component:

$$v(t) = V_{p1} \cos(\omega_1 t + \phi_1) \quad (1)$$

can be estimated by:

$$v(t) = X_1^c \cos(\omega t) + X_1^s \sin(\omega t) \quad (2)$$

or

$$v(t) = \begin{bmatrix} \cos(\omega t) & \sin(\omega t) \end{bmatrix} \begin{bmatrix} X_1^c \\ X_1^s \end{bmatrix} \quad (3)$$

$$v(t) = \varphi \theta \quad (4)$$

where X_1 are the amplitudes to be estimated. In this representation, the amplitudes are functions of V_p and ϕ and described as:

$$X_1^c = V_{p1} \cos \phi_1 \quad (5)$$

$$X_1^s = -V_{p1} \sin \phi_1. \quad (6)$$

Equations (5) and (6) are linear with respect to $v(t)$. Thus, a linear estimation algorithm can be used. In this work, is used a weighted recursive least-squares (RLS) algorithm, where X_m^c and X_m^s relates to the parameters V_p and ϕ by:

$$V_{p1} = \sqrt{(X_1^c)^2 + (X_1^s)^2} \quad (7)$$

$$\phi_1 = -\arctan(X_1^s/X_1^c). \quad (8)$$

For multiple harmonics, the voltage $v(t)$ can be written as follows:

$$v(t) = V_{p1} \cos(\omega_1 t + \phi_1) + V_{p2} \cos(\omega_2 t + \phi_2) + V_{p3} \cos(\omega_3 t + \phi_3) + \dots + V_{pn} \cos(\omega_n t + \phi_n) \quad (9)$$

in which V_{pn} is the amplitude of the n th-harmonic and ϕ_n is the phase-angle.

The matrices φ and θ must be expanded to the form:

$$\varphi = \begin{bmatrix} \cos(\omega_1 t_1) & \sin(\omega_1 t_1) & \dots & \cos(\omega_n t_1) & \sin(\omega_n t_1) \\ \cos(\omega_1 t_2) & \sin(\omega_1 t_2) & \dots & \cos(\omega_n t_2) & \sin(\omega_n t_2) \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix} \quad (10)$$

and

$$\theta = [X_1^c \ X_1^s \ X_2^c \ X_2^s \ \dots \ X_k^c \ X_k^s]^T \quad (11)$$

$$e[n] = v[n] - \hat{v}[n]. \quad (12)$$

The use of the RLS algorithm allows the estimation of the parameters in (11). Thus, the amplitudes and phases of the voltage components are often determined by (7) and (8) respectively. during this way, the worth of the voltage is estimated. For each instant t_n , a mistake of the estimated signal are often calculated by:



$$\hat{\theta}_n = \hat{\theta}_{n-1} + P_n \varphi e[n], \quad (13)$$

The required parameter θ can be estimated by the following equation:

$$P_n = P_{n-1} - \frac{P_{n-1} \varphi \varphi^T P_{n-1}}{1 + \varphi^T P_{n-1} \varphi}. \quad (14)$$

and P_n is the covariance matrix to be updated by:

$$v(t) = v_{pcc}(t) - Ri(t) - L \frac{d}{dt} i(t) + u(t). \quad (15)$$

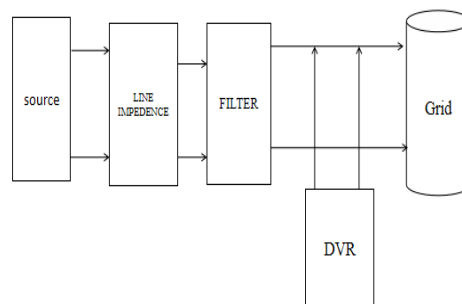
These equations are initialized by taking some initial values for the estimate at instants n , $v(n)$ and P_n . The covariance matrix P_n is typically initialized by $P_n = \alpha I$, where α may be a large number and that i is that the unit matrix.

The RLS algorithm loop consists of solve the equations (12),(13) and (14). The RLS has the advantage doesn't contain delays, common to filters, which improves the performance of the system used.

III. MODEL AND STYLE OF THE DVR SYSTEM

The architecture of the system is shown in Fig.1. this is often an single-phase equivalent circuit to electrical grid compensation scheme to sensitive load. The DVR is found between the grid and therefore the sensitive equipment. The DVR consists of a DCAC converter supported IGBTs, an influence storage system, LC filters and a transformer to inject the voltage at the output of the DVR. The grid voltage, v_{pcc} , is applied on the purpose of common coupling (PCC). the present i provides the sensitive load. The DVR voltage is u and v is that the load voltage. The parameters related to the coupling transform are the resistance R and inductance L . the info acquisition and control system is additionally shown in Fig.1.

The system consists of a sensor to live the load voltage, a measured voltage estimation block, another to calculate the reference voltage for the controller and therefore the controller block. The control action is shipped to the inverter.



BLOCK DIAGRAM



IV. DVR VOLTAGE INJECTION METHOD

This work proposes a way to compensate voltage sags in systems with harmonic distortion. The tactic consists of maintaining the pre-sag voltage level by injecting only voltage with the elemental frequency (f_0). As a result, the DVR compensates sags and reduces the harmonic distortion level at the elemental frequency f_0 .

To maintain the amplitude of the reference voltage, v_{ref}

v_{pcc} , the DVR must know the amplitude of the sagged voltage, v_{f0} . However, the voltage may be a distorted sagged signal described as follows:

The amplitude of the distorted signal are going to be the sum of the values of every harmonic component. With this, it is feasible to obtain the amplitude of the elemental component of the sagged signal, v_{f0} , and thus calculate the voltage (18) that must be injected by the DVR.

The voltage phase injected by the DVR must be an equivalent as the fundamental component of the grid voltage and is estimated using the RLS algorithm proposed. During this way, the voltage injected by the DVR and therefore the grid voltage need to be synchronized. To synchronize the voltages it's necessary to estimate a phase of the load voltage. Figure 3 illustrates an example of the amplitude determination (18) injected by the DVR. Example of voltage sag with harmonic distortion.

This method of voltage injection only compensates the

sagged voltage in distorted voltage systems, these harmonic components aren't compensated by the restorer device. Then, the proposed method has the advantage of generating an easy waveform to compensate only the sag, this enables an extended battery lifetime of the DVR. As a consequence, restoration of the fundamental voltage, besides recomposing it to its nominal value, also attenuates the extent of THD within the load. These statements are validated within the next sections.

V. SIMULATION RESULTS

The simulation results discussed during this paper are carried out through a Simulink platform. A load voltage compensation system was simulated and therefore the grid voltage used was that of Fig. 2. This is often a voltage sag with harmonic distortion. This voltage contains the odd harmonic components until the 13th and is taken into account the standard voltage within the phase. It's worth to analyze the performance of proposed compensation methods. The scenario tested may be a voltage sag with harmonic distortions in one among the phases. The sag of 40% starts at 20 ms and ends at 80 ms. As shown within Fig. 3, the load voltage is compensated and fewer distorted than the pre-sag voltage. The THD of the pre-sag voltage is 33% and at the instant of the DVR operation is reduced to 17%. Thus the DVR restored the dip voltage and improved the standard of the waveform. The fundamental component of the voltage was restored and as a consequence the THD was reduced.

Then, the proposed method was compared with other compensation methods for systems with harmonic distortion and voltage sag. Within the method described by [11], [12], the DVR compensates the sag and mitigates all the consequences of harmonic distortion. The compensation of all distortion effects requires more reactive power than that utilized in the tactic proposed during this paper. Additionally to the very fact that harmonic distortions are permanent regime problems and would require the continual operation of the equipment, which isn't capable of the DVR as the dc-bus is supplied by batteries that only withstand short duration voltage variations.

The comparison of the active DVR powers used in the [11], [12] method, P2, and the method proposed in this paper, P1. The curves of that during fault, in the method proposed used a lower active power to compensate the voltage sagged satisfactorily.

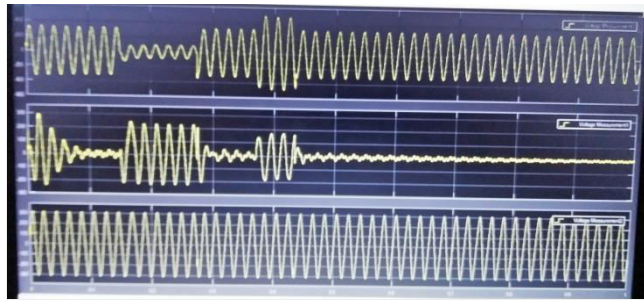
VI. EXPERIMENTAL RESULTS

The experimental platform shown in Fig. 6 was used to verify the simulation results and to validate the compensation method proposed during this work. The DVR setup consists of transformers, LC filters, inverters and a digital signal controller. The most device of the setup may be a four-leg DC-AC Semikron power converter supported IGBTs controlled by the digital signal controller (DSC) TMS320F28335. The data acquisition system consists of Hall effect voltage sensors. All tests were performed in banks of power resistors. A sag voltage generator was used to produce sag and harmonic distortion to be regulated by the DVR control system. The experimental grid voltage on the oscilloscope screen. An equivalent scenario of the simulation is verified, the reference voltage is about 380 V and a sag of 40% is produced in one among the phases. This grid voltage is considered the standard sagged voltage used to analyze the performance of proposed compensation methods.



This is a critical scenario because it contains two different power quality problems. The grid voltage sags, the voltage injected by the DVR and therefore the load voltage. The controlled curve shows that the rated value is achieved from the restoration only of the fundamental component.

As the voltage sag compensation is merely performed with the fundamental component, as shown in Fig. 9(a), the load voltage becomes less distorted, addition to injecting an easy sinusoidal signal, THD is additionally reduced and therefore the load voltage quality is improved.



OUTPUT WAVEFORM

The action of the DVR mitigates the interferences of the harmonics, during this way the grid voltage is restored to a sinusoidal form. Thus, the proposed method had an efficient response and was validated.

The reference voltage level was maintained at the load and only the elemental component was preserved. The result of DVR action, seen in Fig. 11(a), shows that to wipe off the harmonic components of the load voltage it's necessary to inject a voltage with a non-sinusoidal shape.

VII. CONCLUSIONS

This paper proposes a voltage injection method for the DVR and therefore the use of the recursive least-squares technique. The proposed method is in a position to mitigate the voltage sags in systems with harmonic distortion from the grid by injecting only voltage with the elemental frequency. This developed method corrects sags with less active power than the tactic used for compensating entire distortion effect. The utilization of the method described during this work still improves the THD of the signal compared to the pre-sag condition. Simulations and experiments including these distortions were used to verify the proposed system. The result shows the efficiency of the DVR to mitigate voltage sag in systems with harmonic distortion.

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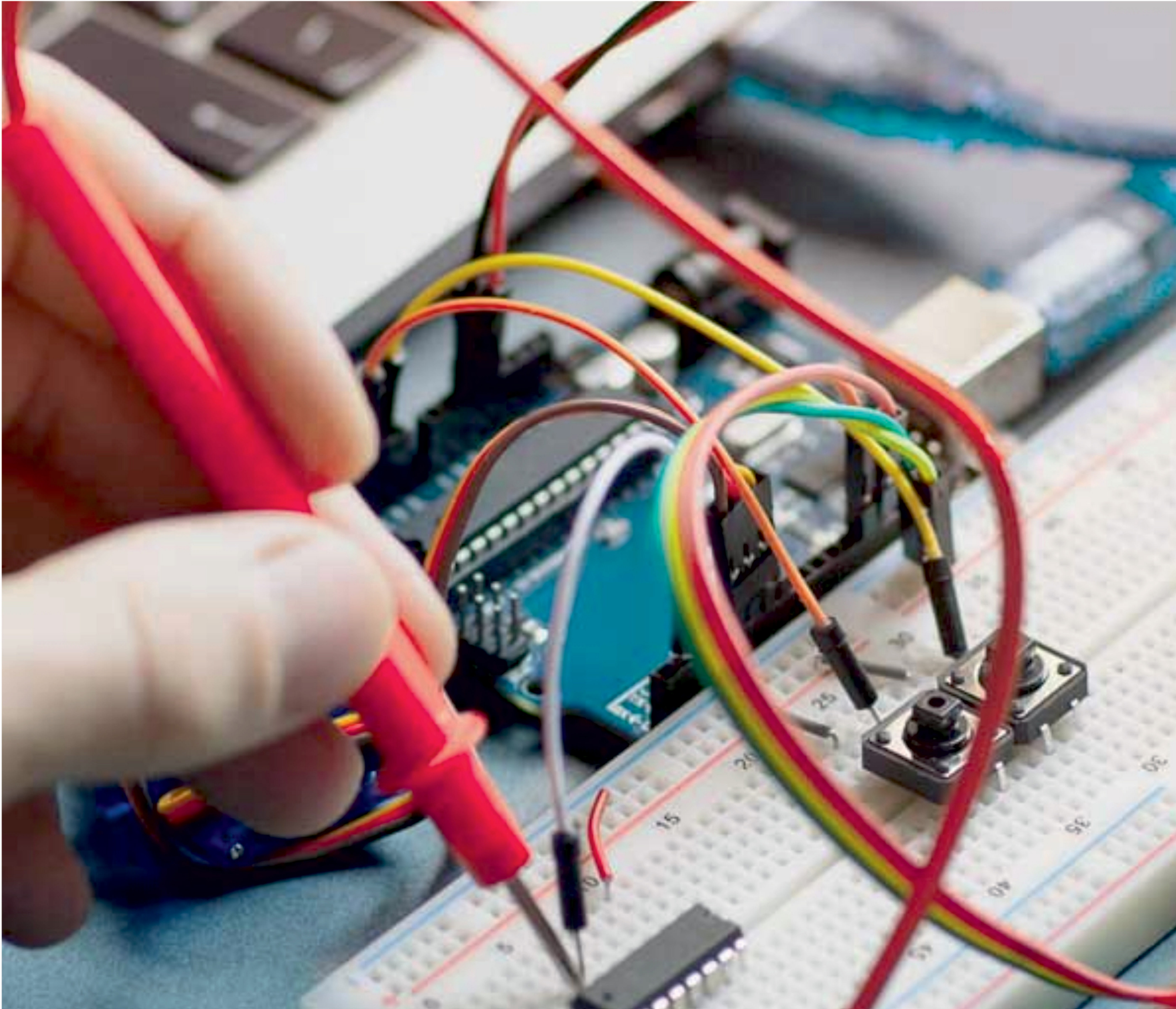
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